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**Development of Luenberger Observer (contd.) and Introduction to Kalman Filtering** Advanced Process Control by Prof.Sachin C.Patwardhan,Department of Chemical Engineering,IIT Bombay.For more details on NPTEL ...

**Introduction to Trajectory Optimization** This video is an introduction to trajectory optimization, with a special focus on direct collocation methods. The slides are from a ...

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is shown that the estimate ...

**Generalised Predictive Control 2\_10 - State space GPC** Looks at how the GPC control law changes if one wants to use a state space model. For convenience, proposes a slightly different ...

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**Exploration vs. Exploitation - Learning the Optimal Reinforcement Learning Policy** Welcome back to this series on reinforcement learning! Last time, we left our discussion of Q-learning

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## **Angelos asset allocation and thoughts on the p2p future** ☐☐

Interview on Angelos channel:

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**Dynamic Optimization Modeling in CasADi** We introduce CasADi, an open-source numerical optimization framework for C++, Python, MATLAB and Octave. Of special ...

## **Future Talk #82HD - Investing in A.I.**

A look at artificial intelligence as a business, current trends in A.I., and A.I.'s potential societal impact. The guest is Kartik Gada, ...

**Which Regulation To Finance Transmission Investment in Electricity? | Vincent Rious & Arthur Henriot** Which regulation to finance

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with Vincent Rious and Arthur Henriot  
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**Generalised predictive control 2.3 -  
The control law** Shows how the GPC  
control law expressed in matrix/vector  
format can be interpreted as being  
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